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Exercises for Lecture  
Real-Time Systems and Applications  
Summer Semester 15

## Exercise Sheet 6

(11 Punkte)

**Exercise Due at Wednesday, June 17, 2015, 12:00 Uhr**

**Hinweise:** Gruppenarbeit von bis zu drei Personen aus der gleichen Übungsgruppe ist möglich. Bitte vergessen Sie nicht Ihre Namen und Ihre Matrikelnummern auf die Lösung zu schreiben. **Die Abgaben können in den beschrifteten Briefkasten vor dem Sekretariat des LS12 (OH16/E22) eingeworfen oder per Mail (PDF Format) an georg.von-der-brueggen [☺] tu-dortmund.de abgegeben werden.**

**Note:** It is allowed to work in a group of up to three persons, if these persons are from the same practice group. Please do not forget to write your name and your Matrikelnummer on the solutions. **The solutions can either be placed in the mailbox in front of the secretary's office of LS 12 (OH/E22) or sent by mail (PDF format) to georg.von-der-brueggen [☺] tu-dortmund.de**

### Exercise Sessions:

Do, 10:15 - 11:45 OH16/E18  
Do, 14:15 - 15:45 OH16/E18

### 6.1 Self-Suspension (2 Punkte)

Prove that the speedup factor of the *Proportional Fixed-Relative Deadline Assignment* for 1-segmented suspension sporadic task systems is at least  $\Omega(n)$ . The assignment is

- $D_{i,1} = \frac{C_{i,1}}{C_{i,1}+C_{i,2}}(T_i - S_i)$
- $D_{i,2} = \frac{C_{i,2}}{C_{i,1}+C_{i,2}}(T_i - S_i)$

**Hint:** If Equal Deadline Assignment (EDA) is feasible, then the optimal schedule is also feasible.

### 6.2 Necessary condition (3 Punkte)

Consider task systems with constrained deadlines.

- Write down the necessary condition for arbitrary self-suspension sporadic task systems under uniprocessor fixed-priority scheduling.
- Write down the sufficient condition for arbitrary self-suspension sporadic task systems under uniprocessor fixed-priority scheduling.

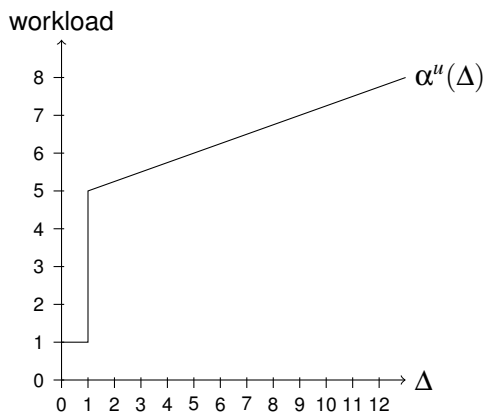
Explain/prove your answer.

### 6.3 RTC (4 Punkte)

1. Mr. Smart wants to define the feasibility of his design as follows: “the system is feasible if  $\alpha^u(\Delta) \leq \beta^l(\Delta)$  for any  $\Delta \geq 0$ ”, where  $\alpha$  and  $\beta$  are arrival curve and service curve, respectively. Is this a reasonable definition?
2. How to derive the arrival curves from a set of given traces of events? How to derive the service curves from a set of traces of services?
3. What are the limitations of using Greedy Processing Components (GPC) in Real-Time Calculus (RTC)? How to perform schedulability analysis for fixed-priority scheduling based on GPCs? For fixed-priority scheduling, what are the similarity and difference of worst-case response time analysis in RTC to and from the time-demand schedulability tests for sporadic real-time tasks with arbitrary deadlines?

Hint: 1+1+2

### 6.4 Real-Time Calculus (1 Punkt)



Is the arrival curve in the left correct? Is it tight? If yes, why? If not, how to make it tighter?

### 6.5 Challenge on Arbitrary Schedules with 1-Segmented Self-Suspension (optional) (1 Punkt)

Prove the following necessary condition for any implicit-deadline arbitrary 1-segmented self-suspension sporadic task model:

$$\forall t > 0, \quad \sum_{\tau_i \in \mathbf{T}} dbf_i^*(t) \leq t. \tag{1}$$

where

$$dbf_i^*(t) = \begin{cases} 0 & 0 \leq t < T_i - S_i \\ C_{i,\max} + \left\lfloor \frac{t - (T_i - S_i)}{T_i} \right\rfloor (C_{i,1} + C_{i,2}) & t \geq T_i - S_i \end{cases} \tag{2}$$

General Hints: