

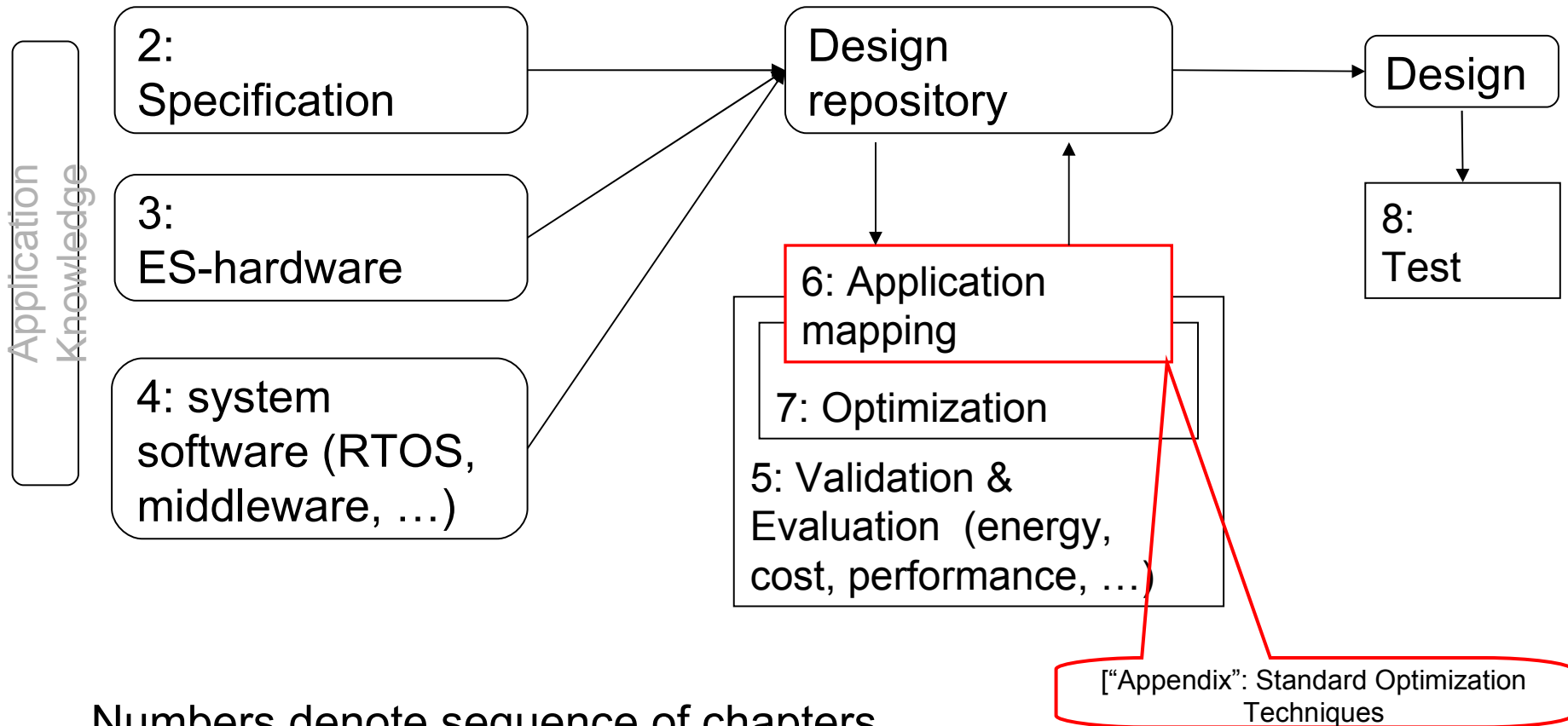
# Standard Optimization Techniques

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# Structure of this course



Numbers denote sequence of chapters

# Integer (linear) programming models

Ingredients:

- Cost function
  - Constraints
- } Involving linear expressions of integer variables from a set  $X$

Cost function  $C = \sum_{x_i \in X} a_i x_i$  with  $a_i \in \mathbb{R}, x_i \in \mathbb{N}$  (1)

Constraints:  $\forall j \in J : \sum_{x_i \in X} b_{i,j} x_i \geq c_j$  with  $b_{i,j}, c_j \in \mathbb{R}$  (2)

**Def.:** The problem of minimizing (1) subject to the constraints (2) is called an **integer (linear) programming (ILP) problem**.

If all  $x_i$  are constrained to be either 0 or 1, the IP problem said to be a **0/1 integer (linear) programming problem**.

# Example

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$$C = 5x_1 + 6x_2 + 4x_3$$

$$x_1 + x_2 + x_3 \geq 2$$

$$x_1, x_2, x_3 \in \{0,1\}$$

$x_1$	$x_2$	$x_3$	$C$
0	1	1	10
1	0	1	9
1	1	0	11
1	1	1	15

← Optimal

# Remarks on integer programming

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- Maximizing the cost function: just set  $C' = -C$
- Integer programming is NP-complete.
- Running times depend exponentially on problem size, but problems of  $>1000$  vars solvable with good solver (depending on the size and structure of the problem)
- The case of  $x_i \in \mathbb{R}$  is called *linear programming* (LP). Polynomial complexity, but most algorithms are exponential, in practice still faster than for ILP problems.
- The case of some  $x_i \in \mathbb{R}$  and some  $x_i \in \mathbb{N}$  is called *mixed integer-linear programming*.
- ILP/LP models good starting point for modeling, even if heuristics are used in the end.
- Solvers: `lp_solve` (public), CPLEX (commercial), ...

# Simulated Annealing

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- General method for solving combinatorial optimization problems.
- Based the model of slowly cooling crystal liquids.
- Some configuration is subject to changes.
- Special property of Simulated annealing:  
Changes leading to a poorer configuration (with respect to some cost function) are accepted with a certain probability.
- This probability is controlled by a temperature parameter: the probability is smaller for smaller temperatures.

# Simulated Annealing Algorithm

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```
procedure SimulatedAnnealing;  
var i, T: integer;  
begin  
  i := 0; T := MaxT;  
  configuration := <some initial configuration>;  
  while not terminate(i, T) do  
    begin  
      while InnerLoop do  
        begin NewConfig := variation(configuration);  
          delta := evaluation(NewConfig, configuration);  
          if delta < 0  
            then configuration := NewConfig;  
            else if SmallEnough(delta, T, random(0,1))  
              then configuration := Newconfiguration;  
        end;  
      T := NewT(i, T); i := i + 1;  
    end; end;
```

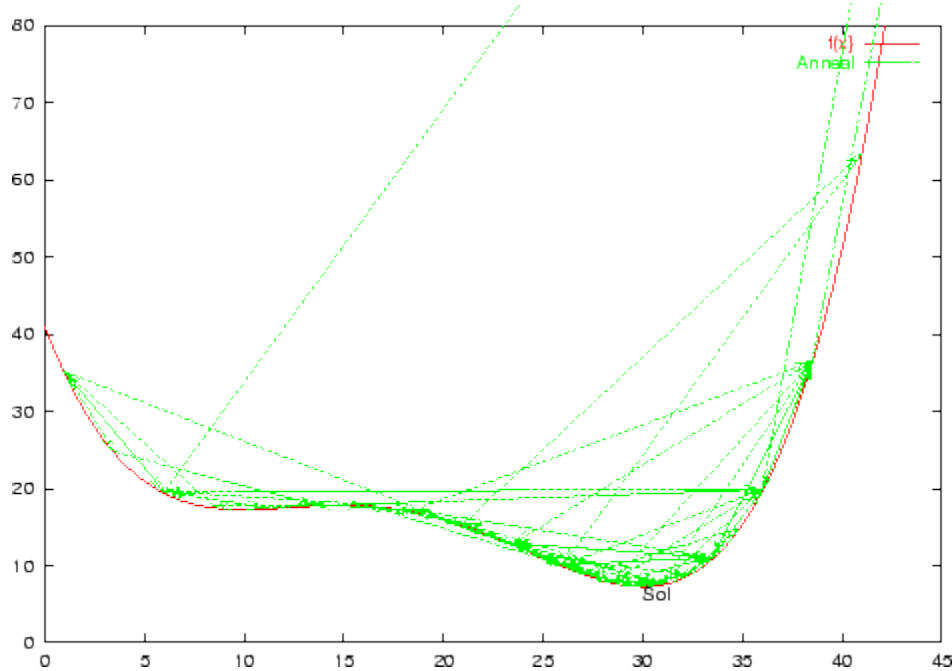
# Explanation

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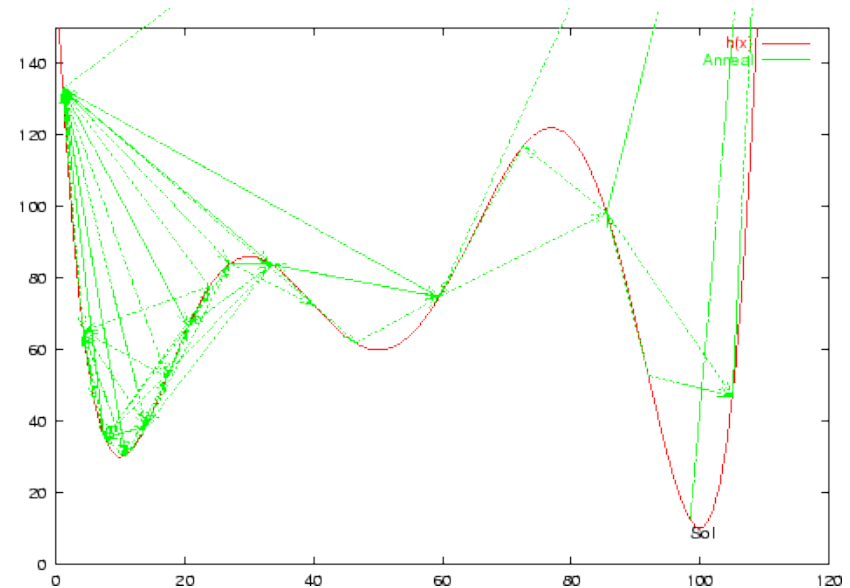
- Initially, some random initial configuration is created.
- Current temperature is set to a large value.
- Outer loop:
  - Temperature is reduced for each iteration
  - Terminated if (temperature  $\leq$  lower limit) or (number of iterations  $\geq$  upper limit).
- Inner loop: For each iteration:
  - New configuration generated from current configuration
  - Accepted if (new cost  $\leq$  cost of current configuration)
  - Accepted with temperature-dependent probability if (cost of new config.  $>$  cost of current configuration).



# Behavior for actual functions



130 steps



200 steps

[[people.equars.com/~marco/poli/phd/node57.html](http://people.equars.com/~marco/poli/phd/node57.html)]

<http://foghorn.cadlab.lafayette.edu/cadapplets/fp/fpIntro.html>

# Performance

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- This class of algorithms has been shown to outperform others in certain cases [Wegener, 2005].
- Demonstrated its excellent results in the TimberWolf layout generation package [Sechen]
- Many other applications ...

# Evolutionary Algorithms (1)

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- **Evolutionary Algorithms** are based on the collective learning process within a population of individuals, each of which represents a search point in the space of potential solutions to a given problem.
- The population is arbitrarily initialized, and it evolves towards better and better regions of the search space by means of randomized processes of
  - **selection** (which is deterministic in some algorithms),
  - **mutation**, and
  - **recombination** (which is completely omitted in some algorithmic realizations).

[Bäck, Schwefel, 1993]

# Evolutionary Algorithms (2)

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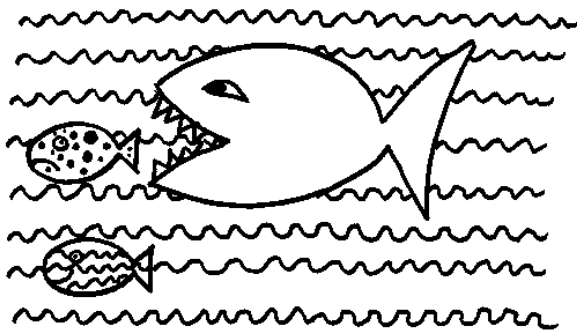
- *The environment (given aim of the search) delivers a quality information (**fitness value**) of the search points, and the selection process favours those individuals of higher fitness to reproduce more often than worse individuals.*
- *The recombination mechanism allows the mixing of parental information while passing it to their descendants, and mutation introduces innovation into the population*

[Bäck, Schwefel, 1993]

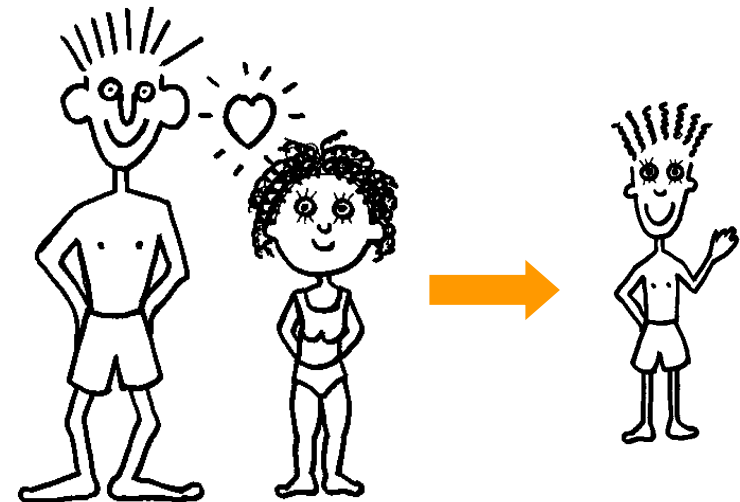
# Evolutionary Algorithms

## Principles of Evolution

### 1 Selection



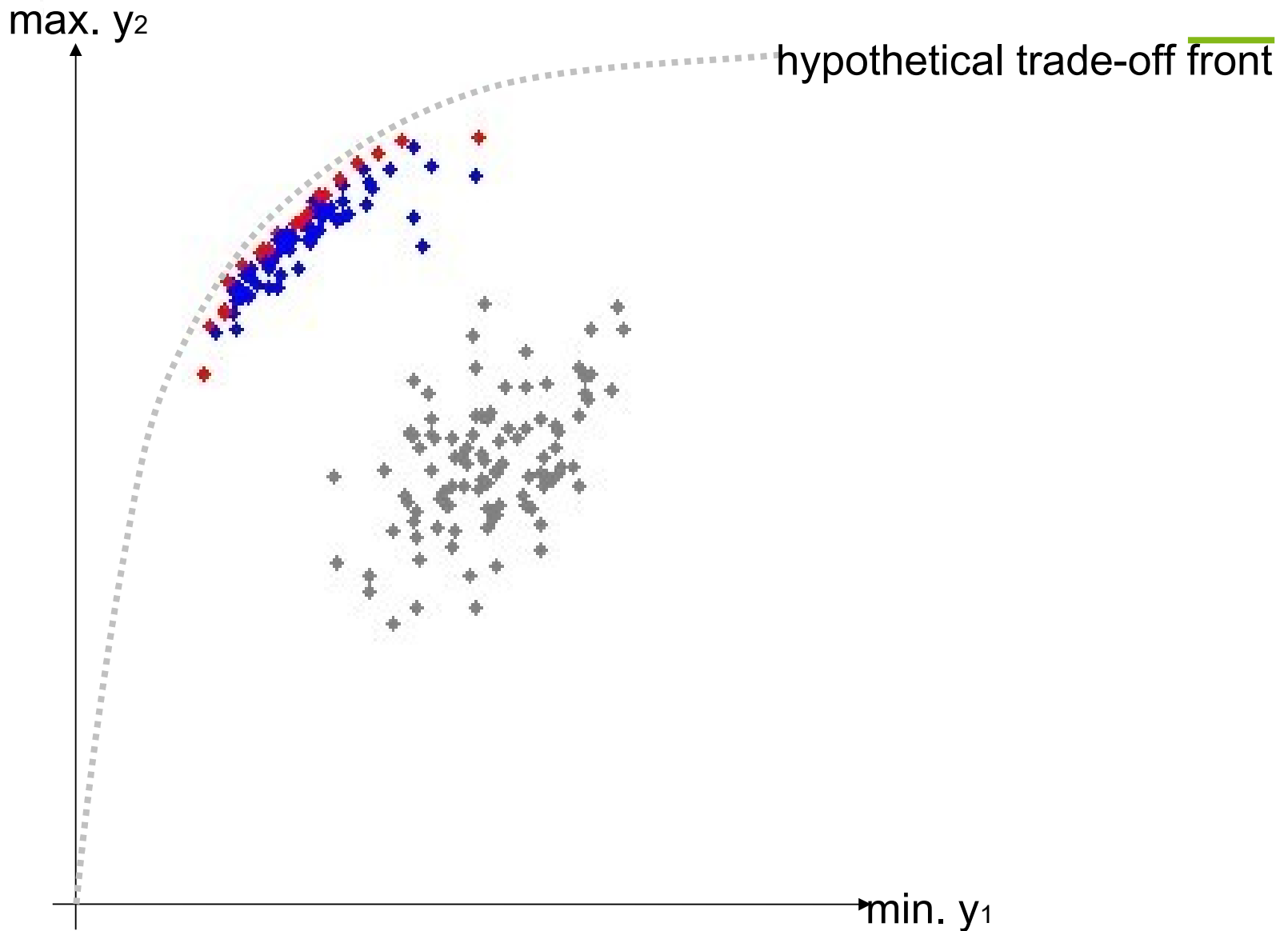
### 3 Cross-over



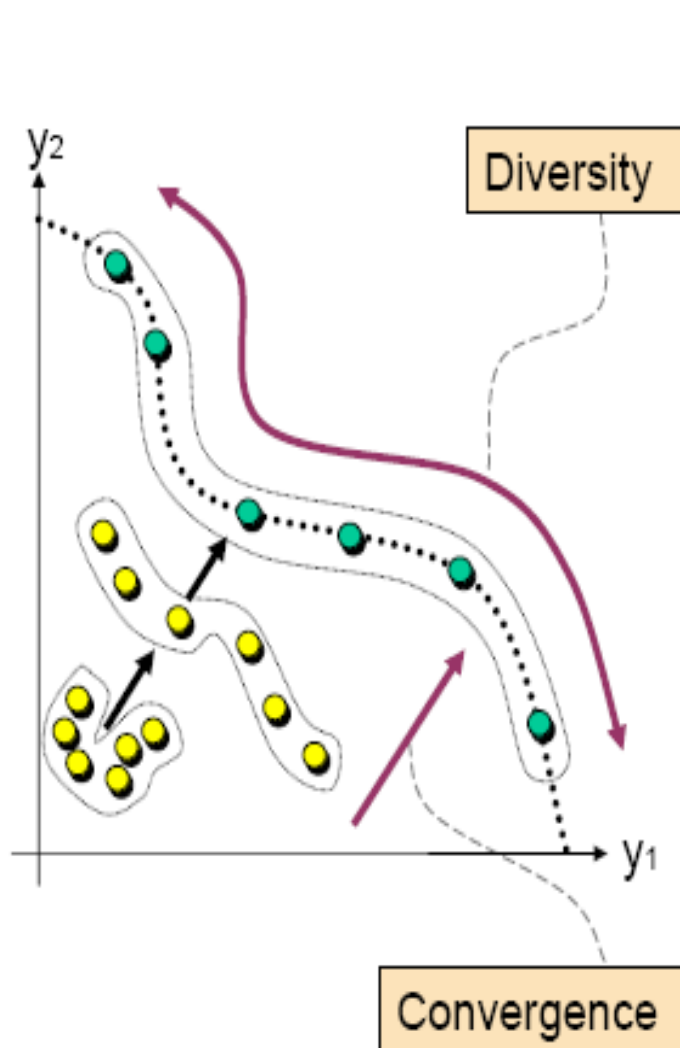
### 2 Mutation



# An Evolutionary Algorithm in Action



# Issues in Multi-Objective Optimization



► How to maintain a diverse Pareto set approximation?

② **density estimation**

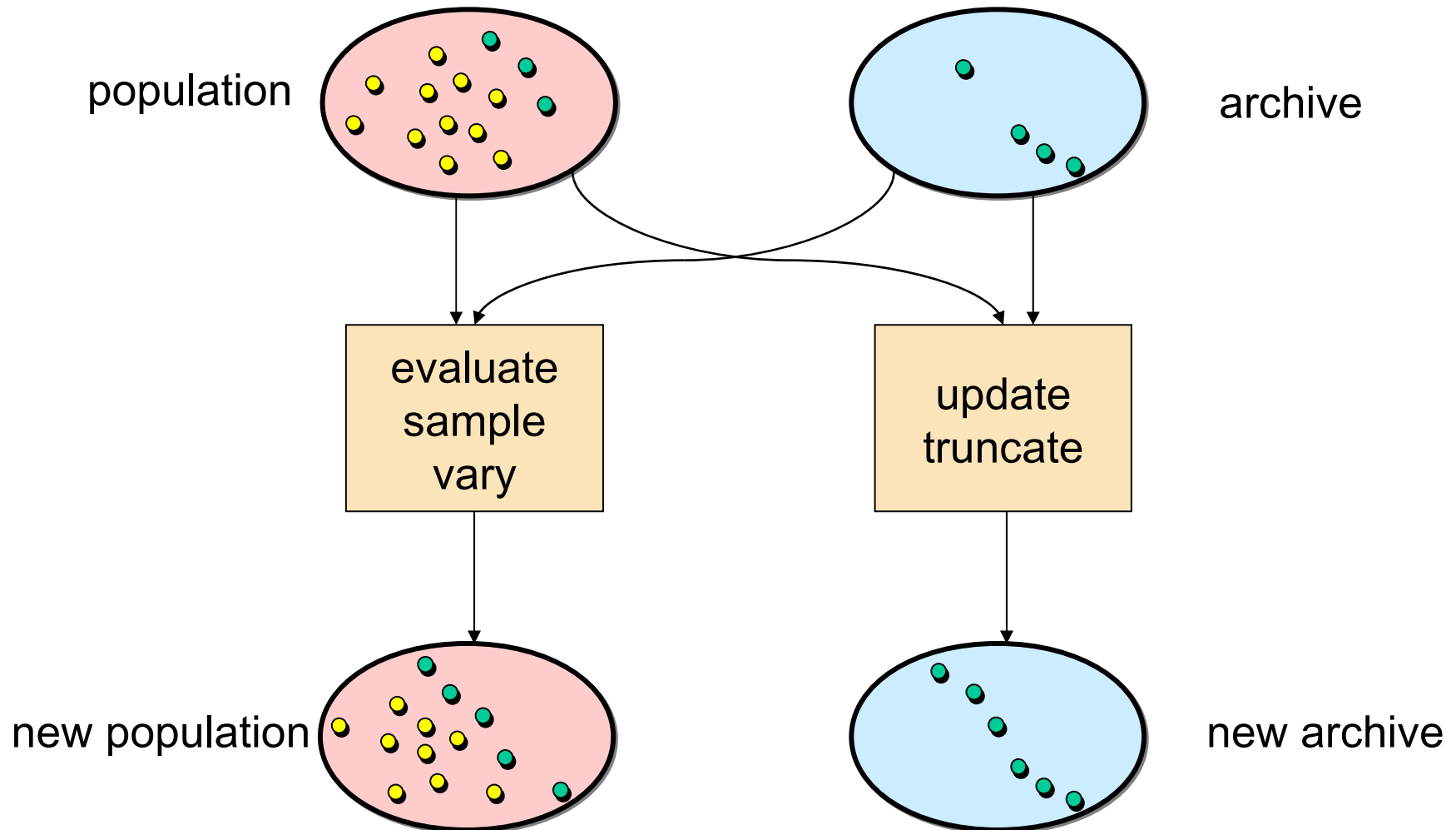
► How to prevent nondominated solutions from being lost?

③ **environmental selection**

► How to guide the population towards the Pareto set?

① **fitness assignment**

# A Generic Multiobjective EA





# Example: SPEA2 Algorithm

- |                |   |
|----------------|---|
| <i>Step 1:</i> | Generate initial population $P_0$ and empty archive (external set) $A_0$ . Set $t = 0$ .  |
| <i>Step 2:</i> | Calculate fitness values of individuals in $P_t$ and $A_t$ .  |
| <i>Step 3:</i> | $A_{t+1}$ = nondominated individuals in $P_t$ and $A_t$ .<br>If size of $A_{t+1} > N$ then reduce $A_{t+1}$ , else if size of $A_{t+1} < N$ then fill $A_{t+1}$ with dominated individuals in $P_t$ and $A_t$ . |
| <i>Step 4:</i> | If $t > T$ then output the nondominated set of $A_{t+1}$ .<br>Stop.   |
| <i>Step 5:</i> | Fill mating pool by binary tournament selection.  |
| <i>Step 6:</i> | Apply recombination and mutation operators to the mating pool and set $P_{t+1}$ to the resulting population. Set $t = t + 1$ and go to Step 2.  |

# Summary

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## Integer (linear) programming

- Integer programming is NP-complete
- Linear programming is faster
- Good starting point even if solutions are generated with different techniques

## Simulated annealing

- Modeled after cooling of liquids
- Overcomes local minima

## Evolutionary algorithms

- Maintain set of solutions
- Include selection, mutation and recombination