

Standard Optimization Techniques

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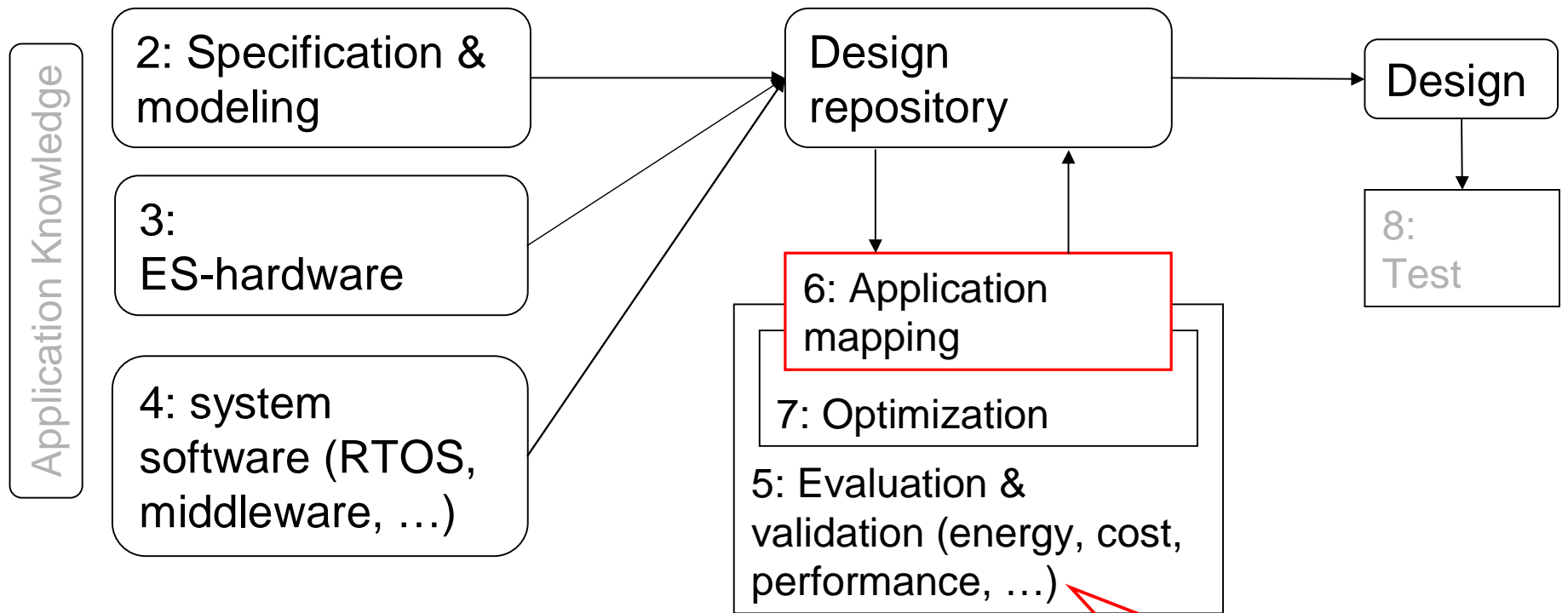


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Structure of this course



Numbers denote sequence of chapters

[“Appendix”: Standard Optimization Techniques]

Integer linear programming models

Ingredients:

- Cost function
 - Constraints
- } Involving linear expressions of integer variables from a set X

Cost function $C = \sum_{x_i \in X} a_i x_i$ with $a_i \in \mathbb{R}, x_i \in \mathbb{N}$ (1)

Constraints: $\forall j \in J : \sum_{x_i \in X} b_{i,j} x_i \geq c_j$ with $b_{i,j}, c_j \in \mathbb{R}$ (2)

Def.: The problem of minimizing (1) subject to the constraints (2) is called an **integer linear programming (ILP) problem**.

If all x_i are constrained to be either 0 or 1, the ILP problem is said to be a **0/1 integer linear programming problem**.

Example

$$C = 5x_1 + 6x_2 + 4x_3$$

$$x_1 + x_2 + x_3 \geq 2$$

$$x_1, x_2, x_3 \in \{0,1\}$$

x_1	x_2	x_3	C
0	1	1	10
1	0	1	9
1	1	0	11
1	1	1	15

← Optimal

Remarks on integer programming

- Maximizing the cost function: just set $C' = -C$
- Integer programming is NP-complete.
- Running times depend exponentially on problem size, but problems of >1000 vars solvable with good solver (depending on the size and structure of the problem)
- The case of $x_i \in \mathbb{R}$ is called *linear programming* (LP). Polynomial complexity, but most algorithms are exponential, in practice still faster than for ILP problems.
- The case of some $x_i \in \mathbb{R}$ and some $x_i \in \mathbb{N}$ is called *mixed integer-linear programming*.
- ILP/LP models good starting point for modeling, even if heuristics are used in the end.
- Solvers: Ip_solve (public), CPLEX (commercial), ...

Evolutionary Algorithms (1)

- **Evolutionary Algorithms** are based on the collective learning process within a population of individuals, each of which represents a search point in the space of potential solutions to a given problem.
- The population is arbitrarily initialized, and it evolves towards better and better regions of the search space by means of randomized processes of
 - **selection** (which is deterministic in some algorithms),
 - **mutation**, and
 - **recombination** (which is completely omitted in some algorithmic realizations).

[Bäck, Schwefel, 1993]

Evolutionary Algorithms (2)

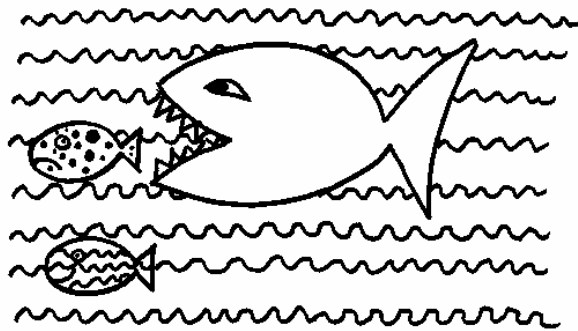
- *The environment (given aim of the search) delivers a quality information (**fitness value**) of the search points, and the selection process favours those individuals of higher fitness to reproduce more often than worse individuals.*
- *The recombination mechanism allows the mixing of parental information while passing it to their descendants, and mutation introduces innovation into the population*

[Bäck, Schwefel, 1993]

Evolutionary Algorithms

Principles of Evolution

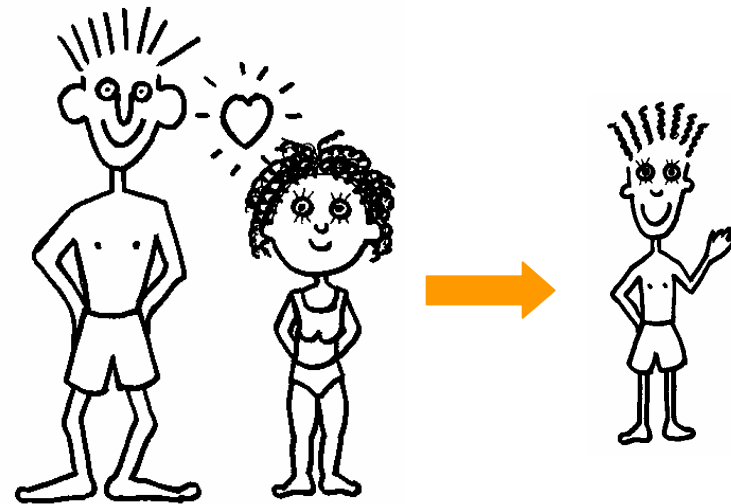
① Selection



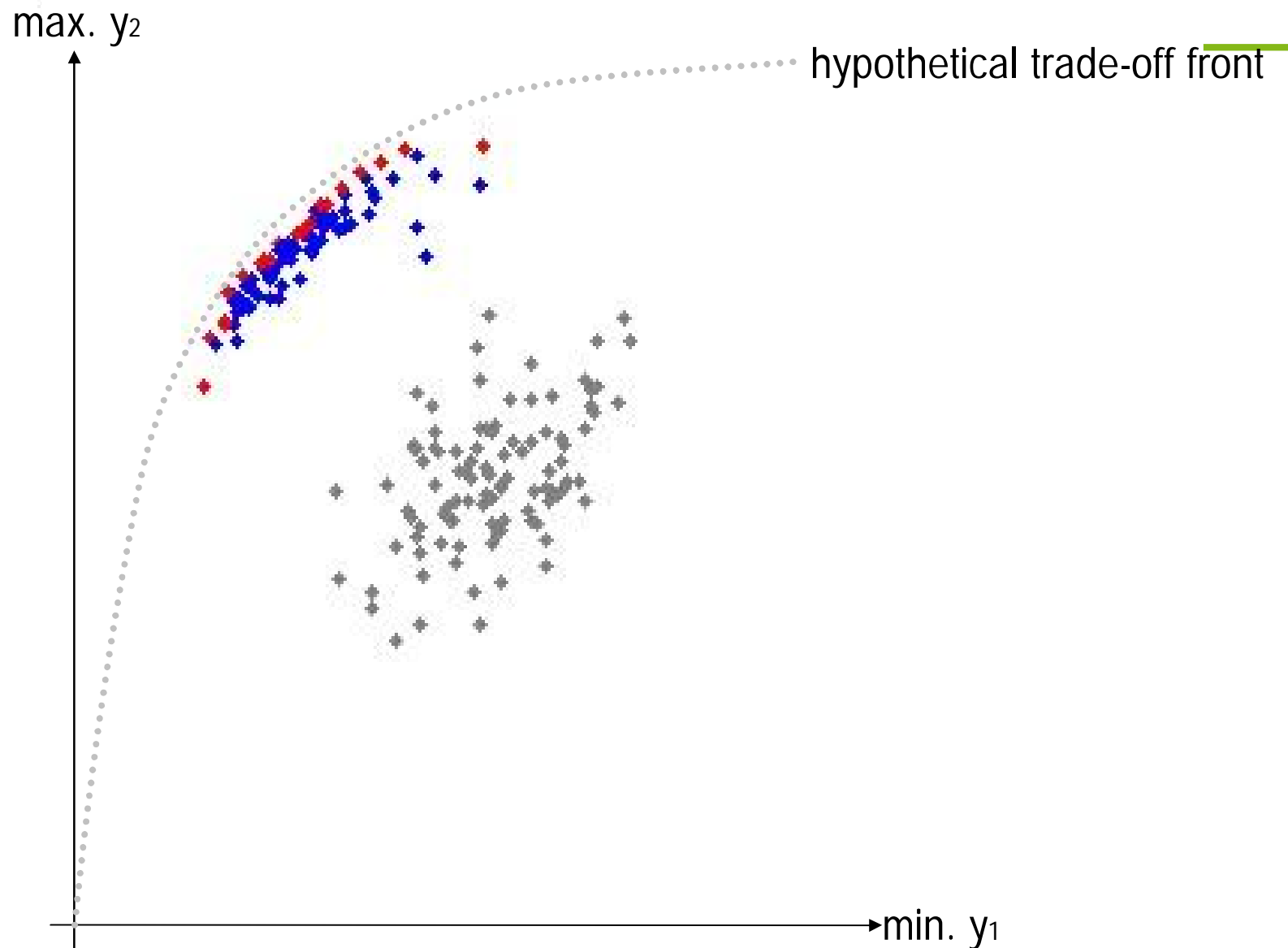
② Mutation



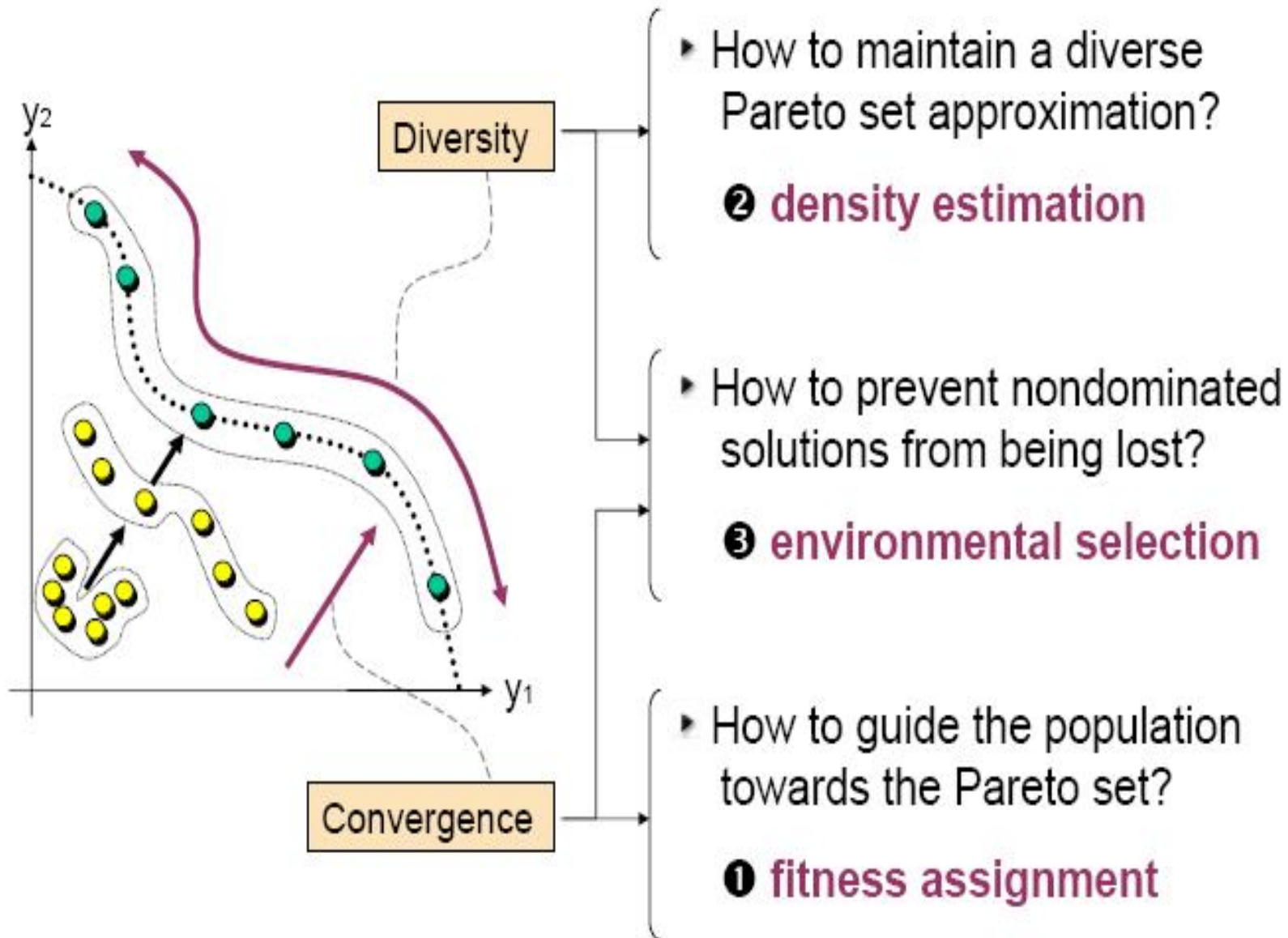
③ Cross-over



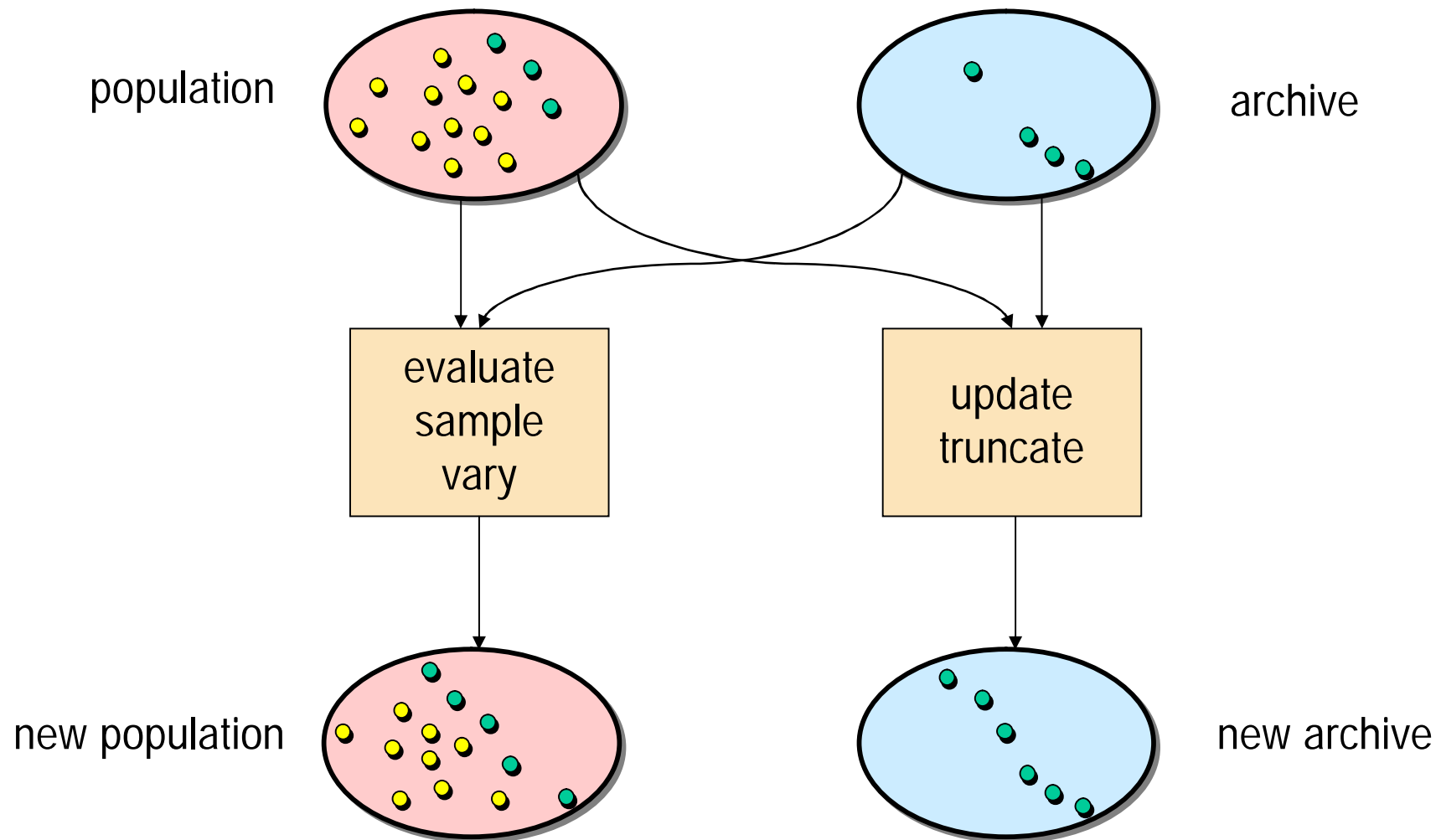
An Evolutionary Algorithm in Action



Issues in Multi-Objective Optimization



A Generic Multiobjective EA



Example: SPEA2 Algorithm

Step 1:	Generate initial population P_0 and empty archive (external set) A_0 . Set $t = 0$.
Step 2:	Calculate fitness values of individuals in P_t and A_t .
Step 3:	A_{t+1} = nondominated individuals in P_t and A_t . If size of $A_{t+1} > N$ then reduce A_{t+1} , else if size of $A_{t+1} < N$ then fill A_{t+1} with dominated individuals in P_t and A_t .
Step 4:	If $t > T$ then output the nondominated set of A_{t+1} . Stop.
Step 5:	Fill mating pool by binary tournament selection.
Step 6:	Apply recombination and mutation operators to the mating pool and set P_{t+1} to the resulting population. Set $t = t + 1$ and go to Step 2.

Summary

Integer (linear) programming

- Integer programming is NP-complete
- Linear programming is faster
- Good starting point even if solutions are generated with different techniques

Simulated annealing

- Modeled after cooling of liquids
- Overcomes local minima

Evolutionary algorithms

- Maintain set of solutions
- Include selection, mutation and recombination