D/A-Converts

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Embedded system hardware is frequently used in a loop ("hardware in a loop"): P. Marwedel

A/D converter
sample–and–hold

sensors

(physical) environment

D/A converter

actuators

display

information processing

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cyber-physical systems
Kirchhoff’s junction rule
Kirchhoff’s Current Law, Kirchhoff’s first rule

Kirchhoff’s Current Law:
At any point in an electrical circuit, the sum of currents flowing towards that point is equal to the sum of currents flowing away from that point.
(Principle of conservation of electric charge)

Formally, for any node in a circuit:

\[ \sum_k i_k = 0 \]

Count current flowing away from node as negative.

Example:

\[ i_1 + i_2 + i_4 = i_3 \]

\[ i_1 + i_2 - i_3 + i_4 = 0 \]

[Jewett and Serway, 2007].
Kirchhoff's loop rule

Kirchhoff's Voltage Law, Kirchhoff's second rule

The principle of conservation of energy implies that:
The sum of the potential differences (voltages) across all elements around any closed circuit must be zero

\[ \sum_k V_k = 0 \]

Formally, for any loop in a circuit:

Count voltages traversed against arrow direction as negative

Example:

\[ V_1 - V_2 - V_3 + V_4 = 0 \]

\[ V_3 = R_3 \times I_3 \] if current counted in the same direction as \( V_3 \)

\[ V_3 = -R_3 \times I_3 \] if current counted in the opposite direction as \( V_3 \)

[Jewett and Serway, 2007].
Operational Amplifiers (Op-Amps)

Operational amplifiers (op-amps) are devices amplifying the voltage difference between two input terminals by a large gain factor $g$.

For an ideal op-amp: $g \to \infty$

(In practice: $g$ may be around $10^4..10^6$)
Digital-to-Analog (D/A) Converters

Various types, can be quite simple, e.g.:

\[ I = x_3 \times \frac{V_{\text{ref}}}{R} + x_2 \times \frac{V_{\text{ref}}}{2 \times R} + x_1 \times \frac{V_{\text{ref}}}{4 \times R} + x_0 \times \frac{V_{\text{ref}}}{8 \times R} = \frac{V_{\text{ref}}}{8 \times R} \times \sum_{i=0}^{3} x_i \times 2^i \]
Current $I$ proportional to the number represented by $x$

Loop rule:

$$x_0 \cdot I_0 \cdot 8 \cdot R + V_- - V_{ref} = 0$$

$$I_0 = x_0 \times \frac{V_{ref}}{8 \times R}$$

In general:

$$I_i = x_i \times \frac{V_{ref}}{2^{3-i} \times R}$$

Junction rule:

$$I = \sum_{i} I_i$$

$$I = x_3 \times \frac{V_{ref}}{R} + x_2 \times \frac{V_{ref}}{2 \times R} + x_1 \times \frac{V_{ref}}{4 \times R} + x_0 \times \frac{V_{ref}}{8 \times R} = \frac{V_{ref}}{8 \times R} \times \sum_{i=0}^{3} x_i \times 2^i$$

$I \sim \text{nat}(x)$, where nat($x$): natural number represented by $x$;
Output voltage proportional to the number represented by $x$

Loop rule*: \[ y + R_1 \times I' = 0 \]

Junction rule°: \[ I = I' \]

\[ y + R_1 \times I = 0 \]

From the previous slide

\[ I = \frac{V_{\text{ref}}}{8 \times R} \times \sum_{i=0}^{3} x_i \times 2^i \]

Hence:

\[ y = -V_{\text{ref}} \times \frac{R_1}{8 \times R} \sum_{i=0}^{3} x_i \times 2^i = -V_{\text{ref}} \times \frac{R_1}{8 \times R} \times \text{nat}(x) \]

Op-amp turns current $I \sim \text{nat}(x)$ into a voltage $\sim \text{nat}(x)$
Output generated from signal $e_3(t)$

* Assuming “zero-order hold”

Possible to reconstruct input signal?
Sampling Theorem

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Possible to reconstruct input signal?

- Assuming Nyquist criterion met
- Let \( \{t_s\}, s = ..., -1, 0, 1, 2, ... \) be times at which we sample \( g(t) \)
- Assume a constant sampling rate of \( 1/p_s (\forall s: p_s = t_{s+1} - t_s) \).
- According sampling theory, we can approximate the input signal as follows:

\[
z(t) = \sum_{s=-\infty}^{\infty} y(t_s) \sin\frac{\pi}{p_s}(t - t_s)
\]

Weighting factor for influence of \( y(t_s) \) at time \( t \)
Called sinc function

[Oppenheim, Schafer, 2009]
Weighting factor for influence of $y(t_s)$ at time $t$

\[ \text{sinc}(t - t_s) = \frac{\sin\left(\frac{\pi}{p_s}(t - t_s)\right)}{\frac{\pi}{p_s}(t - t_s)} \]

No influence at $t_s+n$
Contributions from the various sampling instances
(Attempted) reconstruction of input signal

* Assuming 0-order hold
How precisely are we reconstructing the input?

\[
z(t) = \sum_{s=-\infty}^{\infty} y(t_s) \cdot \frac{\sin \frac{\pi}{T_s}(t-t_s)}{\frac{\pi}{T_s}(t-t_s)}
\]

- **Sampling theory:**
  - Reconstruction using \( \text{sinc}() \) is precise

- However, it may be impossible to really compute \( z(t) \) as indicated ….
How to compute the $sinc(\cdot)$ function?

\[
z(t) = \sum_{s=-\infty}^{\infty} y(t_s) \sin \frac{\pi}{T_s} \left( t - t_s \right)
\]

- **Filter theory**: The required interpolation is performed by an ideal low-pass filter ($sinc$ is the Fourier transform of the low-pass filter transfer function)

Filter removes high frequencies present in $y(t)$
Limitations

\[ z(t) = \sum_{s=-\infty}^{\infty} \frac{y(t_s) \sin \frac{\pi}{T_s} (t - t_s)}{\pi \frac{T_s}{T_s} (t - t_s)} \]

- Actual filters do not compute \( \text{sinc}(\cdot) \)
  In practice, filters are used as an approximation. Computing good filters is an art itself!

- All samples must be known to reconstruct \( e(t) \) or \( g(t) \).
  \( \overset{\rightleftharpoons}{\text{Waiting indefinitely before we can generate output!}} \)
  In practice, only a finite set of samples is available.

- Actual signals are never perfectly bandwidth limited.

- Quantization noise cannot be removed.
Actuators/Display
Embedded system hardware is frequently used in a loop ("hardware in a loop"): 

- A/D converter
  - sample-and-hold
  - sensors
  - (physical) environment
- information processing
- display
- D/A converter
- actuators

Cyber-physical systems
Output devices of embedded systems include

- **Displays**: Display technology is extremely important. Major research and development efforts

- **Electro-mechanical devices**: these influence the environment through motors and other electro-mechanical equipment. Frequently require analog output.
Actuators

Huge variety of actuators and output devices, impossible to present all of them. Motor as an example
Actuators (2)

Courtesy and ©: E. Obermeier, MAT, TU Berlin

http://www.piezomotor.se/pages/PWtechnology.html
Secure Hardware

- Security needed for communication & storage
- Demand for special equipment for cryptographic keys
- To resist side-channel attacks like
  - measurements of the supply current or
  - Electromagnetic radiation.

Special mechanisms for physical protection (shielding, sensor detecting tampering with the modules).

- Logical security, using cryptographic methods needed.
- Smart cards: special case of secure hardware
  - Have to run with a very small amount of energy.
- In general, we have to distinguish between different levels of security and knowledge of “adversaries”
Summary

Hardware in a loop

- Sensors
- Discretization
- Information processing
  - Importance of energy efficiency, Special purpose HW very expensive, Energy efficiency of processors, Code size efficiency, Run-time efficiency
  - Reconfigurable Hardware

- Communication
- D/A converters
- Sampling theorem
- Actuators (briefly)
- Secure hardware (briefly)